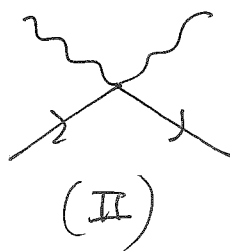
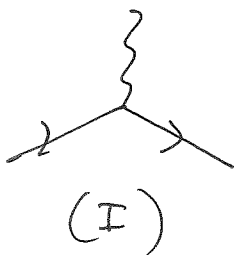


$$1a) \mathcal{L}_0 = -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \partial_\mu \psi^\dagger \partial^\mu \psi - m^2 \psi^\dagger \psi$$

$$\mathcal{L}_I = -ie A_\mu (\psi^\dagger \partial^\mu \psi - \partial^\mu \psi^\dagger \psi) + e^2 A_\mu A^\mu \psi^\dagger \psi$$

(I)
(II)



$$1b) Z[J, J^\dagger, J_\mu] = \int \mathcal{D}A_\mu \int \mathcal{D}\psi \int \mathcal{D}\psi^\dagger e^{i \int d^4x \{ \mathcal{L}_0 + \mathcal{L}_I + J^\dagger \psi + \psi^\dagger J + J_\mu A^\mu \}}$$

$$= \int \mathcal{D}A_\mu \int \mathcal{D}\psi \int \mathcal{D}\psi^\dagger e^{i \int d^4x \{ \mathcal{L}_0 + J^\dagger \psi + \psi^\dagger J + J_\mu A^\mu \}} \cdot \left(1 + i \int d^4w \mathcal{L}_I(w) + \frac{1}{2!} i^2 \int d^4w_1 \int d^4w_2 \mathcal{L}_I(w_1) \mathcal{L}_I(w_2) + \dots \right)$$

Note that

$$\psi(w) e^{i \int d^4x \{ \mathcal{L} + J^\dagger \psi \}} = \frac{\delta}{\delta i J^\dagger(w)} e^{i \int d^4x \{ \mathcal{L} + J^\dagger \psi \}}$$

$$\psi^\dagger(w) e^{i \int d^4x \{ \mathcal{L} + J^\dagger \psi \}} = \frac{\delta}{\delta i J(w)} e^{i \int d^4x \{ \mathcal{L} + J^\dagger \psi \}}$$

$$A_\mu(w) e^{i \int d^4x \{ \mathcal{L} + J_\mu A^\mu \}} = \frac{\delta}{\delta i J_\mu(w)} e^{i \int d^4x \{ \mathcal{L} + J_\mu A^\mu \}}$$

to rewrite Z as follows:

$$Z[J, J^\dagger, J_\mu] = e^{i \int d^4w \mathcal{L}_I \left(\frac{\delta}{\delta i J_\mu(w)}, \frac{\delta}{\delta i J^\dagger(w)}, \frac{\delta}{\delta i J(w)} \right)} Z_0[J, J^\dagger, J_\mu]$$

where

$$Z_0[J, J^\dagger, J_\mu] = Z_0[0, 0, 0] e^{-\frac{i}{2} \int d^4x \int d^4y J_\mu(x) \Delta^{\mu\nu}(x-y) J_\nu(y) - i \int d^4x \int d^4y J^\dagger(x) D(x-y) J(y)}$$

$$\mathcal{L}_I \left(\frac{\delta}{\delta i J_\mu}, \frac{\delta}{\delta i J^\dagger}, \frac{\delta}{\delta i J} \right) = -ie \frac{\delta}{\delta i J_\mu} \left(\frac{\delta}{\delta i J} \partial_\mu \frac{\delta}{\delta i J^\dagger} - \dots \right) + e^2 \left(\frac{\delta}{\delta i J_\mu} \right)^2 \frac{\delta}{\delta i J^\dagger} \frac{\delta}{\delta i J}$$

$$2) \quad \bar{\psi}' = \psi'^{\dagger} \gamma^0 = \left(e^{-\frac{i\alpha\gamma_5}{2}} \psi \right)^{\dagger} \gamma^0 = \psi^{\dagger} e^{\frac{i\alpha\gamma_5}{2}} \gamma^0 = \bar{\psi} \gamma^0 e^{\frac{i\alpha\gamma_5}{2}} \gamma^0$$

$$= \bar{\psi} e^{-\frac{i\alpha\gamma_5}{2}}$$

where we used in order $\gamma_5^{\dagger} = \gamma_5$, $\gamma^0{}^2 = 1$, $\{\gamma_5, \gamma^0\} = 0$ and $2n+1$

$$\gamma^0 e^{\frac{i\alpha\gamma_5}{2}} \gamma^0 = \gamma^0 \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{i\alpha}{2} \right)^n \gamma_5^n \gamma^0 = \sum_{n=0}^{\infty} \frac{1}{(2n)!} \left(\frac{i\alpha}{2} \right)^{2n} - \gamma_5 \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left(\frac{i\alpha}{2} \right)^{2n+1}$$

$$= e^{-\frac{i\alpha\gamma_5}{2}}$$

or in infinitesimal form $= \gamma^0 \left(1 + \frac{i\alpha\gamma_5}{2} + O(\alpha^2) \right) \gamma^0 =$

$$= 1 - \frac{i\alpha\gamma_5}{2} + O(\alpha^2) = e^{-\frac{i\alpha\gamma_5}{2}}$$

We show that

$$\mathcal{L}(q_1', q_2', \psi', \bar{\psi}') = \mathcal{L}(q_1, q_2, \psi, \bar{\psi})$$

The transformation $(q_1, q_2) \rightarrow (q_1', q_2')$ is a rotation in the (q_1, q_2) plane ($SO(2)$).

The scalar part of \mathcal{L} is manifestly invariant under $SO(2)$ because it only depends on the invariant $q_1^2 + q_2^2$ (show it explicitly)

The Dirac term is invariant under a chiral transformation

$$(\bar{\psi} i \not{\partial} \psi)' = \bar{\psi} e^{-\frac{i\alpha\gamma_5}{2}} i \not{\partial} e^{\frac{i\alpha\gamma_5}{2}} \psi = \bar{\psi} i \not{\partial} \psi \quad \{\gamma_5, \not{\partial}\} = 0$$

$$+ g \bar{\psi}' (q_1 + i\gamma_5 q_2) \psi' = g \bar{\psi} e^{-\frac{i\alpha\gamma_5}{2}} (\cos\alpha + i\gamma_5 \sin\alpha) (q_1 + i\gamma_5 q_2) e^{\frac{i\alpha\gamma_5}{2}} \psi$$

Then use (*) $\cos\alpha + i\gamma_5 \sin\alpha = e^{i\alpha\gamma_5}$ to obtain

$$= g \bar{\psi} e^{-\frac{i\alpha\gamma_5}{2}} e^{i\alpha\gamma_5} e^{\frac{i\alpha\gamma_5}{2}} (q_1 + i\gamma_5 q_2) \psi = g \bar{\psi} (q_1 + i\gamma_5 q_2) \psi$$

Thus \mathcal{L} is invariant.

(*) Show it by using the Hint.

$$3) \partial_\mu J_5^\mu = \partial_\mu (\bar{\psi} \gamma^\mu \gamma_5 \psi) = \bar{\psi} \overleftarrow{\partial} \gamma_5 \psi + \bar{\psi} \overrightarrow{\partial} \gamma_5 \psi$$

$$= \bar{\psi} \overleftarrow{\partial} \gamma_5 \psi - \bar{\psi} \gamma_5 \overrightarrow{\partial} \psi$$

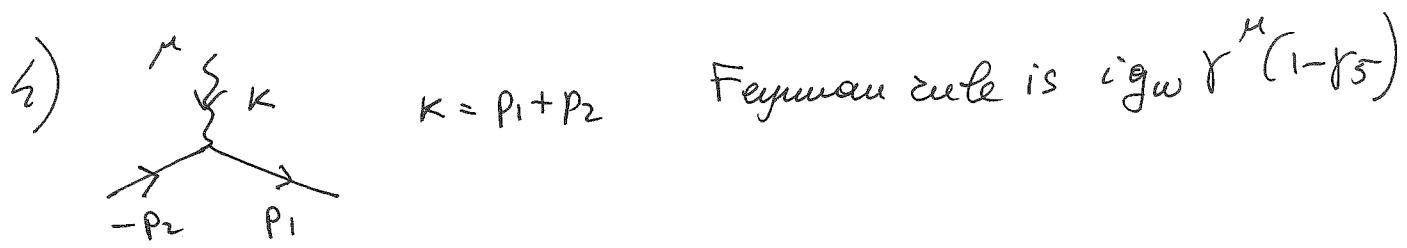
On the EoM one obtains

$$\partial_\mu J_5^\mu = i \bar{\psi} (e \not{A} + m) \gamma_5 \psi + i \bar{\psi} \gamma_5 (e \not{A} + m) \psi$$

$$= ie \bar{\psi} \{ \not{A}, \gamma_5 \} \psi + 2im \bar{\psi} \gamma_5 \psi$$

$$= 2im \bar{\psi} \gamma_5 \psi$$

since $\{ \not{A}, \gamma_5 \} = 0$



$$A = ig_w \bar{u}_2(p_1) \gamma^\mu (1-\gamma_5) v_{\bar{e}1}(p_2) \epsilon_\mu^S(k)$$

$$A^\dagger = -ig_w \bar{v}_{\bar{e}1}(p_2) \gamma^\nu (1-\gamma_5)^\dagger \gamma^0 u_2(p_1) \epsilon_\nu^S(k) \quad (\epsilon \text{'s real})$$

$$= -ig_w \bar{v}_{\bar{e}1}(p_2) \gamma^\nu (1-\gamma_5) u_2(p_1) \epsilon_\nu^S(k)$$

NB $\gamma^0 (\gamma^\nu (1-\gamma_5))^\dagger \gamma^0 = \gamma^0 (1-\gamma_5) \gamma^{\nu\dagger} \gamma^0 = (1+\gamma_5) \gamma^0 \gamma^{\nu\dagger} \gamma^0 = (1+\gamma_5) \gamma^\nu = \gamma^\nu (1-\gamma_5)$

$$X = \frac{1}{3} g_w^2 \sum_{z, z'=1,2} (\bar{u}_z(p_1) \gamma^\mu (1-\gamma_5) v_{\bar{e}1}(p_2)) (\bar{v}_{\bar{e}1}(p_2) \gamma^\nu (1-\gamma_5) u_z(p_1)) \times$$

$$\times \left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right)$$

$$= \frac{1}{3} g_w^2 T_2 \left[\not{p}_1 \gamma^\mu (1-\gamma_5) \not{p}_2 \gamma^\nu (1-\gamma_5) \right] \left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right)$$

$$= \frac{2}{3} g_w^2 T_2 [(1-\gamma_5) \not{p}_2 \gamma^\nu \not{p}_1 \gamma^\mu] \left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right)$$

NB $(1-\gamma_5)^2 = 2(1-\gamma_5)$ $(1+\gamma_5)^2 = 2(1+\gamma_5)$

The terms with γ_5 do not contribute because

$T_2 [\gamma_5 \gamma^\mu \gamma^\nu \gamma^\alpha \gamma^\beta] \propto \epsilon^{\mu\nu\alpha\beta}$ is totally antisymmetric
and it is contracted with the totally symmetric $\left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right)$

you can also show it explicitly:

$$\begin{aligned} T_2 [\gamma_5 \not{p}_2 \gamma^\nu \not{p}_1 \gamma^\mu] \left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right) &= \\ &= -T_2 [\gamma_5 \not{p}_2 \gamma^\mu \not{p}_1 \gamma_\mu] + \frac{1}{M^2} T_2 [\gamma_5 \not{p}_2 \not{k} \not{p}_1 \not{k}] \\ &= 2 T_2 [\gamma_5 \not{p}_2 \not{p}_1] + \frac{1}{M^2} T_2 [\gamma_5 \not{p}_2 (2 p_1 \cdot k \not{k} - k^2 \not{p}_1)] \\ &= 0 \end{aligned}$$

where we used $\gamma^\mu \not{p}_1 \gamma_\mu = -2 \not{p}_1$
 $\not{k} \not{p}_1 \not{k} = 2 p_1 \cdot k \not{k} - k^2 \not{p}_1$

and $T_2 [\gamma_5 \gamma^\mu \gamma^\nu] = 0$

$$\begin{aligned} X &= \frac{2}{3} g_w^2 T_2 [\not{p}_2 \gamma^\nu \not{p}_1 \gamma^\mu] \left(-g_{\mu\nu} + \frac{k_\mu k_\nu}{M^2} \right) = \\ &= \frac{2}{3} g_w^2 \left\{ -T_2 [\not{p}_2 \gamma^\mu \not{p}_1 \gamma_\mu] + \frac{1}{M^2} T_2 [\not{p}_2 \not{k} \not{p}_1 \not{k}] \right\} \\ &= \frac{2}{3} g_w^2 \cdot 4 \left\{ 2 p_1 \cdot p_2 + \frac{2}{M^2} (p_1 \cdot k)(p_2 \cdot k) - \frac{1}{M^2} M^2 p_1 \cdot p_2 \right\} \\ &= \frac{8}{3} g_w^2 \left\{ p_1 \cdot p_2 + \frac{2}{M^2} (p_1 \cdot k)(p_2 \cdot k) \right\} \end{aligned}$$

$$K = p_1 + p_2 \quad K = (M, \vec{0}) \quad p_1 = (E, \vec{p}) \quad p_2 = (E, -\vec{p}) \quad \underline{z}$$

$$p_1^2 = p_2^2 = 0 \quad E = |\vec{p}|$$

$$K^2 = (p_1 + p_2)^2 \text{ implies } 2p_1 \cdot p_2 = M^2 \quad \text{thus } p_1 \cdot p_2 = \frac{M^2}{2}$$

$$\text{Energy conservation implies } E = \frac{M}{2} \text{ and}$$

$$p_1 \cdot K = p_2 \cdot K = EM = \frac{M^2}{2}$$

$$\text{Thus } X = \frac{8}{3} g_w^2 M^2$$

and

$$\Gamma^2 = \frac{1}{16\pi} \frac{1}{M} X = \frac{1}{6\pi} g_w^2 M$$